Nonlocal fractional Monge-Ampère equations

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The fractional Laplacian

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Any linear transformation $L : \mathbb{R}^n \to \mathbb{R}^n$ is given by multiplication by a matrix:

L(x) = Ax $x \in \mathbb{R}^n$

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More generally, for s > 0,

$$A^{s} = P^{T} \operatorname{diag}(\lambda_{1}^{s}, \ldots, \lambda_{n}^{s})P$$

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$$e^{-tA} = \sum_{k=0}^{\infty} \frac{(-tA)^k}{k!}$$
$$= P^T \left[\sum_{k=0}^{\infty} \frac{(-tD)^k}{k!} \right] P$$
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Here

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This exponential solves a "heat equation":

$$egin{cases} \partial_t(e^{-tA}) = -A(e^{-tA}) & ext{for all } t>0 \ e^{-tA}ig|_{t=0} = \mathit{Id} \end{cases}$$

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Fractional matrices and exponentials

It is easy to verify that for any $\lambda > 0$ and 0 < s < 1

$$\lambda^{s} = c_{s} \int_{0}^{\infty} \left(e^{-t\lambda} - 1
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Thus,

$$\begin{aligned} A^{s} &= P^{T} \operatorname{diag}(\lambda_{1}^{s}, \dots, \lambda_{n}^{s})P \\ &= c_{s}P^{T} \operatorname{diag}\left[\int_{0}^{\infty} (e^{-t\lambda_{1}} - 1) \frac{dt}{t^{1+s}}, \dots, \int_{0}^{\infty} (e^{-t\lambda_{n}} - 1) \frac{dt}{t^{1+s}}\right]P \\ &= c_{s}\int_{0}^{\infty} \left[P^{T} \operatorname{diag}(e^{-t\lambda_{1}} - 1, \dots, e^{-t\lambda_{n}} - 1)P\right] \frac{dt}{t^{1+s}} \\ &= c_{s}\int_{0}^{\infty} \left[P^{T} \operatorname{diag}(e^{-t\lambda_{1}}, \dots, e^{-t\lambda_{n}})P - P^{T}(Id)P\right] \frac{dt}{t^{1+s}} \\ &= c_{s}\int_{0}^{\infty} \left[e^{-tA} - Id\right] \frac{dt}{t^{1+s}} \end{aligned}$$

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Inverse matrices and exponentials

Clearly, for $\lambda > 0$,

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▶ Using e^{-tA} we can also compute the matrices A^{-s} , s > 0.

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Property 2. Derivatives correspond to multiplication by polynomials:

$$D^k u \quad \longleftrightarrow \quad (i\xi)^k \mathcal{F}(u)$$

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Obviously: $(-\Delta)^1 u = -\Delta u$, $(-\Delta)^0 u = u$, $(-\Delta)^{s_1} [(-\Delta)^{s_2} u] = (-\Delta)^{s_1+s_2} u$

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Then $e^{t\Delta}u(x)$ solves the heat equation

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Moreover, the exponential is given by convolution with the heat kernel

$$e^{t\Delta}u(x) = \int_{\mathbb{R}^n} \frac{e^{-|x-y|^2/(4t)}}{(4\pi t)^{n/2}} u(y) \, dy$$

In this case we use:
$$|\xi|^{2s} = c_s \int_0^\infty \left(e^{-t|\xi|^2} - 1 \right) \frac{dt}{t^{1+s}} \quad (0 < s < 1)$$

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▶ Nonlocal - Fractional order 0 < 2s < 2

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- ► See S., User's guide to the fractional Laplacian and the method of semigroups, Handbook of Fractional Calculus with Applications, Vol. 2, De Gruyter, 2019.

Consider a one-dimensional particle that takes a step of size h > 0 either to the left or to the right with probability 1/2.

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After rearranging,

$$u(x + h) + u(x - h) - 2u(x) = 0$$

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If we divide by h^2 and take the limit as $h \rightarrow 0$,

$$\frac{u(x+h) + u(x-h) - 2u(x)}{h^2} \to \frac{d^2}{dx^2}u(x) = 0$$

so that u is a harmonic function.

A particle that jumps to any point $x \pm kh$ (not only the adjacent ones) with probability depending on how far it jumped:

$$u(x) = \sum_{k \in \mathbb{Z}} u(x - kh) K(kh)$$

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Question(s).

$$\sum_{k\in\mathbb{Z}} \big(u(x)-u(x-kh)\big) K(kh) \to \int_{\mathbb{R}} \frac{u(x)-u(x-y)}{|y|^{1+2s}} \, dy \quad \text{as } h \to 0$$

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- ▶ Who is K?
- ▶ Smoothness of *u*?
- Rate of convergence?

▶ Ciaurri, Roncal, S., Torrea and Varona (Adv. Math. 2018)

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► Ciaurri, Roncal, S., Torrea and Varona (*Adv. Math.* 2018)
We proved that if L = -∆_h (second order differences operator) then

$$(-\Delta_h)^s u(x) = \sum_k \left(u(x) - u(x - hk) \right) K_s(hk)$$

where the kernel is explicit:

$$K_s(hk) = c_s rac{\Gamma(|k|-s)}{h^{2s}\Gamma(|k|+1+s)}$$

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► Ciaurri, Roncal, S., Torrea and Varona (*Adv. Math.* 2018) We proved that if $L = -\Delta_h$ (second order differences operator) then

$$(-\Delta_h)^s u(x) = \sum_k (u(x) - u(x - hk)) K_s(hk)$$

where the kernel is explicit:

$$K_s(hk) = c_s rac{\Gamma(|k|-s)}{h^{2s}\Gamma(|k|+1+s)}$$

We showed, for example, that if $u \in C^{0,\alpha}$ and $2s < \alpha$ then

$$\|(-\Delta_h)^s u - (-\Delta)^s u\|_{\ell_h^\infty} \leq C[u]_{C^\alpha} h^{\alpha-2s}$$

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We also proved approximation of continuous problems $(-\Delta)^s u = f$ by discrete problems $(-\Delta_h)^s u_h = f_h$, under **minimal regularity** of f, and with **explicit rates** of convergence in the L^{∞} -**norm**.

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In general, a nonlocal equation is an equation of the form

$$\int_{\Omega} (u(x) - u(y)) K(x, y) \, dy = f(x)$$

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Models.

• Peridynamics: fracture.

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- Image processing: digital images are discontinuous functions.
• Singular kernels. For 0 < s < 1,

$$K(x,y) = rac{c}{|x-y|^{n+2s}}$$
 for $x, y \in \mathbb{R}^n$

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• Singular kernels. For 0 < s < 1,

$$\mathcal{K}(x,y) = rac{c}{|x-y|^{n+2s}} \qquad ext{for } x,y \in \mathbb{R}^n$$

Then

$$c\int_{\mathbb{R}^n}\frac{u(x)-u(y)}{|x-y|^{n+2s}}\,dy=(-\Delta)^s u(x)$$

is the fractional Laplacian.

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• Compact support. In peridynamics,

$$K(x,y) = \chi_{|x-y| \le \delta} F(x-y)$$

and δ is called the *horizon*.

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• Exponential decay. For $C, c, \alpha > 0$

$$K(x,y) = Ce^{-c|x-y|^{\alpha}}$$

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The Monge-Ampère equation

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The MA equation is the fully nonlinear equation

 $\det(D^2u(x))=f(x)$

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The MA equation is the fully nonlinear equation

 $\det(D^2u(x))=f(x)$

Take a directional derivative ∂_e of the equation to get

trace $\left(\det(D^2 u)(D^2 u)^{-1}D^2(\partial_e u)\right) = \partial_e f$

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Take a directional derivative ∂_e of the equation to get

trace $\left(\det(D^2 u)(D^2 u)^{-1}D^2(\partial_e u)\right) = \partial_e f$

Here $A_u(x) = \det(D^2 u(x))(D^2 u(x))^{-1}$ is the matrix of cofactors of $D^2 u(x)$.

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If we call $v = \partial_e u$ and $g = \partial_e f$ then v solves the linearized MA equation

 $trace(A_u(x)D^2v) = g$

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The MA equation is the fully nonlinear equation

 $\det(D^2u(x))=f(x)$

Take a directional derivative ∂_e of the equation to get

trace $\left(\det(D^2 u)(D^2 u)^{-1}D^2(\partial_e u)\right) = \partial_e f$

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This is an **elliptic equation** (meaning $A_u(x) > 0$) as soon as

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▶ Elliptic MA equation and convexity go together.

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The MA equation is a concave function of D^2u .

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The MA equation is a concave function of $D^2 u$. Claim. If u is convex and C^2 then

$$n[\det(D^2u(x))]^{1/n} = \inf \left\{ \Delta(u \circ A)(A^{-1}x) : A = A^T > 0, \ \det(A) = 1 \right\}$$
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MA is degenerate elliptic. In dimension n = 2, matrices of the form

$${f A}=egin{pmatrix}arepsilon&0\0&1/arepsilon\end{pmatrix}$$

enter in the computation of the infimum.

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Conclusion. The matrices *A* have minimum eigenvalue uniformly bounded below away from zero and, therefore, above away from infinity: **uniform ellipticity**.

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Nonlocal fractional Monge-Ampère equations

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For 1/2 < s < 1 and u linear at infinity, Caffarelli–Charro (2015) defined

$$\mathcal{D}_{s}u(x) = \inf\left\{-(-\Delta)^{s}(u \circ A)(A^{-1}x) : A = A^{T} > 0, \det(A) = 1\right\}$$

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By using the integral formula for the fractional Laplacian,

$$\mathcal{D}_{s}u(x) = \inf_{A > 0, \det(A) = 1} c \int_{\mathbb{R}^{n}} \frac{u(x - y) - u(x)}{|A^{-1}y|^{n + 2s}} \, dy$$

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$$n[\det(D^2u(x))]^{1/n} = \inf\left\{\Delta(u \circ A)(A^{-1}x) : A = A^T > 0, \ \det(A) = 1\right\}$$
$$= \inf\left\{\operatorname{trace}(A^2D^2u(x)) : A = A^T > 0, \ \det(A) = 1\right\}$$

For 1/2 < s < 1 and u linear at infinity, Caffarelli–Charro (2015) defined

$$\mathcal{D}_s u(x) = \inf \left\{ -(-\Delta)^s (u \circ A) (A^{-1}x) : A = A^T > 0, \det(A) = 1 \right\}$$

By using the integral formula for the fractional Laplacian,

$$\mathcal{D}_{s}u(x) = \inf_{A > 0, \det(A) = 1} c \int_{\mathbb{R}^{n}} \frac{u(x - y) - u(x)}{|A^{-1}y|^{n + 2s}} \, dy$$

It can be proved that

$$\lim_{s\to 1^-}\mathcal{D}_s u(x) = n[\det(D^2 u(x))]^{1/r}$$

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▶ This fractional MA operator is **degenerate elliptic**.

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Caffarelli and Charro considered the Dirichlet problem

$$\begin{cases} \mathcal{D}_s \bar{u} = \bar{u} - \phi & \text{in } \mathbb{R}^n \\ \lim_{|x| \to \infty} (\bar{u} - \phi)(x) = 0 \end{cases}$$

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$$\bar{u} > \phi$$
 in \mathbb{R}^n

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Thus, \bar{u} is Lipschitz, semiconcave and

$$\mathcal{D}_s \bar{u} \ge \eta_0 > 0$$
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 in a ball B .

Under these conditions, they proved that the equation becomes **uniformly** elliptic: there exists $\lambda > 0$ such that, for $x \in B$,

$$\mathcal{D}_{s}\bar{u}(x) = \mathcal{D}_{s}^{\lambda}\bar{u}(x) = \inf_{A > \lambda Id, \det(A)=1} c \int_{\mathbb{R}^{n}} \frac{\bar{u}(x-y) - \bar{u}(x)}{|A^{-1}y|^{n+2s}} dy$$

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▶ The uniformly elliptic regularity theory of Caffarelli–Silvestre applies.

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Obstacle problem for fractional MA equation

We consider the obstacle problem

$$\begin{cases} \mathcal{D}_{s} u \geq u - \phi & \text{ in } \mathbb{R}^{n} \\ u \leq \psi & \text{ in } \mathbb{R}^{n} \\ \mathcal{D}_{s} u = u - \phi & \text{ in } \{u < \psi\} \\ \lim_{|x| \to \infty} (u - \phi)(x) = 0 \end{cases}$$

for an obstacle ψ such that

 $\psi > \phi$ and $\psi \leq \overline{u}$ in some compact set.

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Theorem (with Y. Jhaveri, Comm. PDE 2020)

There exists a unique viscosity solution u that is Lipschitz and semiconcave with constants depending only on ϕ and ψ . Moreover

 $u > \phi$ in \mathbb{R}^n

In particular, locally, the problem becomes uniformly elliptic. Higher regularity of u and regularity of the free boundary $\partial \{u < \psi\}$.

Pablo Raúl Stinga (Iowa State University)

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Nonlocal uniformly elliptic equations

We have

$$\mathcal{D}_{s}^{\lambda}u(x) = \inf_{A > \lambda Id, \det(A) = 1} c \int_{\mathbb{R}^{n}} \frac{u(x - y) - u(x)}{|A^{-1}y|^{n+2s}} dy$$

= $-\inf_{A > \lambda Id, \det(A) = 1} (-\operatorname{trace}(A^{2}D^{2}))^{s}u(x)$
= $-(-\operatorname{trace}(B(x)D^{2}))^{s}u(x) = -(-L)^{s}u(x)$

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Theorem (with M. Vaughan, PhD thesis 2020, arXiv preprint)

Suppose that B(x) is uniformly elliptic and Hölder continuous. If $u \ge 0$ is a classical solution to $(-L)^s u = f$ in B_1 then

$$\sup_{B_{1/2}} u \leq C \Big(\inf_{B_{1/2}} u + \|f\|_{L^{\infty}(B_1)} \Big).$$

Moreover, solutions to $(-L)^{s}u = f$ are locally Hölder continuous.

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Under the semigroup setting given by Galé-Miana-S. in J. Evol. Equ. 2012, we developed a new method of sliding paraboloids for singular/degenerate PDEs.

Recall that $v = \partial_e u$ solves the linearized MA equation

 $Lv = \operatorname{trace}(\operatorname{det}(D^2 u)(D^2 u)^{-1}D^2 v) = \operatorname{trace}(A_u(x)D^2 v) = g$

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$$(-L)^{s}v = (-\operatorname{trace}(A_{u}(x)D^{2}))^{s}v$$

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Theorem (with D. Maldonado, Calc. Var. PDE 2017)

Assume that u is convex and sufficiently regular. Under certain geometric conditions, if $v \ge 0$ is a classical solution to $(-L)^s v = f$ in S_1 , v = 0 on ∂S_1 , then

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▶ Under the semigroup setting given by Galé–Miana–S. in *J. Evol. Equ.* 2012, we exploit the divergence and nondivergence structures of the equation.

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Thank you for your attention!

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